

Programming Book for CDP1802 Microprocessor Kit

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The source code was assembled with A18 assembler format. For keypad monitor, we can enter hex code to the memory and test run directly.

With terminal connected at 9600 8n1 asynchronous mode, key LOAD and DUMP can be used to load Intel HEX file and display memory contents easily. For terminal connected, 1ms delay for character and line will be needed.

Program 1 Q LED blinking

```
F001          DELAY: EQU 0F001H

8000          ORG 8000H

8000  F8 F0 B3 F8      LOAD R3, DELAY
8004  01 A3

8006  7B          LOOP: SEQ
8007  D3          SEP R3
8008  7A          REQ
8009  D3          SEP R3
800A  30 06      BR LOOP
```

The subroutine DELAY is located at F001. We use R3 as the pointer. Main program is forever loop running. SEQ makes Q LED lit then call subroutine delay with SEP R3 instruction. REQ, clears Q Flip-flop, Q LED will be turned off. BR LOOP, branch back to LOOP location at 8006.

Enter the hex code from 8000 to 800B. Press PC, then GO.

What is happening?

LOAD R3, DELAY is a built-in macro of the A18 assembler. It produces the 1802 instructions as follows:

```
F8 F0      LDI HIGH(DELAY)
B3         PHI R3
F8         LDI LOW(DELAY)
A3         PLO R3
```

Can we change blinking rate? How?

Here is the list of delay subroutine.

```
F000 D0      RET_DELAY: SEP R0
F001 F8 64   DELAY:  LDI 100
F003 A6      PLO R6
F004 F8 00   DELAY1: LDI 0
F006 A7      PLO R7
F007 27      DELAY2: DEC R7
F008 87      GLO R7
F009 3A 07   BNZ DELAY2
F00B 26      DEC R6
F00C 86      GLO R6
F00D 3A 04   BNZ DELAY1
F00F 30 00   BR RET_DELAY
```

The delay subroutine is automatically loaded on RESET. We can use it by simple calling with SEP register easily.

The subroutine use R6 and R7 making simple delay by counting inner loop with R7 and outer loop by R6.

To change blinking rate, we can modify the byte at F002.

Try change it from 64 to 20. After changed, press PC then GO.
(If you press RESET, 64 will be reloaded)

What is happening?

Program 2 GPIO1 LED

GPIO1 LED is the 8-bit binary display LED. It is another useful device for program debugging. We can display the contents of CPU registers by writing it to GPIO1 location directly.

```
F001          DELAY: EQU 0F001H
7000          GPIO1: EQU 7000H

8000          ORG 8000H

8000  F8 F0 B3 F8      LOAD R3, DELAY
8004  01 A3
8006  F8 70 B4 F8      LOAD R4, GPIO1
800A  00 A4

800C  15          LOOP: INC R5    ; INCREMENT R5
800D  85          GLO R5      ; GET LOW BYTE OF R5
800E  54          STR R4      ; WRITE D TO GPIO1
800F  D3          SEP R3      ; CALL DELAY
8010  30 0C       BR LOOP     ; JUMP TO LOOP
```

The delay subroutine pointer is loaded to R3 and the location of gpio1 is loaded to R4.

Main loop will increment R5. The low byte of R5 is copied to D register. Then write D register to gpio1 LED pointed to by R4.

Delay makes slow counting. Then repeat the loop.

Enter hex code from 8000 to 8011, press PC then GO.

What is happening? Can you change running rate faster? How?

Program 3 LOAD IMMEDIATE 8-bit to D register

```
7000          GPIO1: EQU 7000H

8000          ORG 8000H

8000 F8 70 B4 F8      LOAD R4, GPIO1
8004 00 A4

8006 F8 1F          LDI 1FH
8008 54            STR R4
8009 00            IDL
```

D is the accumulator register. Most instructions use D to pass or to compute the 8-bit data.

LDI 1FH, load immediate 8-bit data to the D register. We use GPIO1 LED to display register D contents. Thus STR R4 instruction will store D register to the location of gpio1 LED.

IDL is IDLE instruction. It will wait for interrupt or DMA operation.

Enter the code from 8000 to 8009. Press PC then GO.

What is happening?

Can you change R4 to R5? How?

Try modify load value from 1F to others, within the range of 00-FF.

Program 4 Running with BREAK POINT

```
2756          BREAK: EQU 2756H
8000          ORG 8000H
8000 F8 1F          LDI 1FH
8002 C0 27 56      LBR BREAK
```

The monitor program provides subroutine to save CPU registers to USER registers. We can use it by LONG BRANCH instruction to BREAK location.

We can examine after program execution with key REG and hex key 0-F.

Enter the code from 8000 to 8004. Press PC then GO.

Press REG, 0 to see register D content.

The method can be applied to R3 to R15 as well.

(User code running will use R0 for program counter, R1 for interrupt vector, and R2 for STACK pointer)

LBR BREAK is available only for saving CPU registers to user registers after user program has been executed.

Key GO will not load user registers to CPU registers!

Program 5 16-bit Binary Addition

2756		BREAK: EQU 2756H
8000		ORG 8000H
8000	F8 12 B3 F8	LOAD R3,1234H ; R3 = 1234H
8004	34 A3	
8006	83	GLO R3
8007	FC 34	ADI 34H
8009	A3	PLO R3
800A	93	GHI R3
800B	7C 12	ADCI 12H
800D	B3	PHI R3 ; R3 = R3+1234H
800E	C0 27 56	LBR BREAK

R3 is loaded with 16-bit constant, 1234H. Suppose we want to add a number 1234H to R3 and put result to R3. The low byte of R3, 34H is first added with 34H, then save the result to the low byte of R3.

The high byte now is then added using ADCI 12H, add with carry flag, DF. And put result back to high byte of R3. LBR BREAK returns control to monitor program and save the R3 to USER register R3.

Enter the code, test run it and examine the result in R3 using key REG, 3.

What is the result of addition?

You can compare with hand calculation.

Program 6 EF flag Testing

```
F001          DELAY: EQU 0F001H
7000          GPIO1: EQU 7000H

8000          ORG 8000H

8000 F8 F0 B3 F8      LOAD R3, DELAY
8004 01 A3
8006 F8 70 B4 F8      LOAD R4, GPIO1
800A 00 A4

800C F8 00          LDI 0
800E A5            PLO R5
800F 54            STR R4

8010 34 10      LOOP: B1 $ ; PRESSED
8012 D3          SEP R3 ; DEBOUNCE

8013 3C 13      BN1 $ ; NO PRESSED
8015 D3          SEP R3 ; DEBOUNCE

8016 15          INC R5 ; DO TASK
8017 85          GLO R5
8018 54          STR R4

8019 30 10      BR LOOP ; REPEAT
```

CDP1802 chip has 4 external flag pins i.e. EF1, EF2, EF3 and EF4. The kit provides EF1 and EF2 on the keyboard. All of these bits are pull-up to logic HIGH. When pressed, the logic will be LOW.

Test program will test EF1 pin. However the internal circuit of the CDP1802 uses negative logic.

We can use short branch instructions B1 and BN1 for testing it.

B1 tests for if EF1=1 (for negative logic EF1 pin must be LOW).
BN1 tests for if EF1=0 (EF1 pin must be HIGH).

Below shows the datasheet descriptions, and instruction hex codes, 34 and 3C.

SHORT BRANCH IF EF1 = 1 ($\overline{\text{EF1}} = V_{SS}$)	B1	34
SHORT BRANCH IF EF1 = 0 ($\overline{\text{EF1}} = V_{CC}$)	BN1	3C

Main program first tests EF1 pin with B1 instruction.

If key was pressed, keep reading EF1. If key released, then call delay to prevent key bounce.

BN1 instruction will test EF1 if no pressed, keep reading EF1. If key was pressed, debounce, then increment R5, write R5 to gpio1 LED.

Enter the code, test run it.

What is happening?

Modify the code, use EF2 instead? How?

Program 7 Timer interrupt

```
7000          GPIO1: EQU 7000H
FFFF          TICK: EQU 0FFFFH

8000          ORG 8000H

8000 F8 80 B1 F8      LOAD R1, INT_VECTOR
8004 18 A1
8006 F8 70 B4 F8      LOAD R4, GPIO1
800A 00 A4
800C F8 FF B6 F8      LOAD R6, TICK
8010 FF A6

8012 E0              SEX R0
8013 70              RET  ; ENABLE INTERRUPT
8014 00              DB 0

8015 30 15          BR $

8017          EXIT_INT:
8017 70              RET  ; R2 = R2 +1, P = R0

8018          INT_VECTOR:      ; P = R1, X =R2

8018 22              DEC R2
8019 78              SAV  ; SAVE T, P=0

801A 06              LDN R6
801B FC 01          ADI 1
801D 56              STR R6
801E FB 0A          XRI 10
8020 3A 26          BNZ NEXT_INC
```

8022	56	STR R6
8023	15	INC R5
8024	85	GLO R5
8025	54	STR R4
8026	C4	NEXT_INC: NOP
8027	30 17	BR EXIT_INT

This program demonstrates the use of 10ms tick for testing the CDP1802 interrupt. SW1 when set to 10ms tick, the tick signal will tie to pin 36, INTRPT.

Main code initializes R1 for interrupt vector, R4 for gpio1 LED, and R6 for tick variable. Then enable interrupt, and repeat jump at location 8015.

The interrupt vector is located at 8018. When interrupt occurs, R2 the stack pointer must be decrement then save the X and P bits to stack memory.

Tick variable then was tested, if equal 10 (10x10ms) then clear it. Increment R5, then write the low of R5 to gpio1 LED.

On return, R2 will be incremented by 1, and program counter will be reloaded with P bits, back to R0.

Enter the code and test run with SW1 set to 10ms tick.

What is happening? Can you change the counting rate to 1Hz?
How?

Program 8 SCANNING DISPLAY

```
7000          GPIO1: EQU 7000H
7102          SEGMENT: EQU 7102H
7101          DIGIT: EQU 7101H

8000          ORG 8000H

8000 F8 80 B3 F8  START: LOAD R3, DELAY
8004 34 A3
8006 F8 71 B4 F8      LOAD R4, SEGMENT
800A 02 A4
800C F8 71 B5 F8      LOAD R5, DIGIT
8010 01 A5

8012 F8 80 BA F8  MAIN: LOAD R10, BUFFER
8016 3D AA
8018 F8 80 BB F8      LOAD R11, SCAN_DIGIT
801C 43 AB

801E F8 06          LDI 6
8020 A8            PLO R8  ; LOOP COUNT

8021 0B          LOOP: LDN R11  ; GET DIGIT CONTROL
8022 FB FF          XRI 0FFH ; complement it
8024 55          STR R5  ; WRITE TO DIGIT

8025 0A          LDN R10  ; GET BYTE FROM BUFFER

8026 54          STR R4  ; WRITE TO SEGMENT
8027 D3          SEP R3  ; DELAY
8028 F8 00          LDI 0  ; TURN OFF DISPLAY
```

```

802A 54          STR R4

802B 1A          INC R10 ; NEXT BUFFER
802C 1B          INC R11 ; NEXT DIGIT

802D 28          DEC R8
802E 88          GLO R8
802F 3A 21       BNZ LOOP ; UNTIL 6 DIGITS

8031 30 12       BR MAIN

8033 D0          RET_DELAY: SEP R0

8034 F8 01       DELAY: LDI 1
8036 A7          PLO R7

8037 27          DELAY1: DEC R7
8038 87          GLO R7
8039 3A 37       BNZ DELAY1

803B 30 33       BR RET_DELAY

803D 37 8F 85 85 BUFFER: DB 37H, 8FH, 85H, 85H,
                0A3H, 0 ; HELLO

8041 A3 00

8043 20 10 08 04 SCAN_DIGIT: DB 20H,10H,8,4,2,1
8047 02 01

```

Kit has 6-digit seven segment display. The segments for all digits are connected together. To display for 6 digits, display scanning will be needed. Each digit is controlled by common pin which is active LOW. Segment is active HIGH.

Display buffer located at 803D-8042 stores display pattern, "HELLO".

Digit control bytes are stored at 8043-8048.

Scanning is made with ACTIVE the digit control, then write the pattern to the segment, and delay, then turn segment off.

Repeat until 6 digits. The display will show still pattern, "HELLO".

Enter hex code 8000-8048. Press PC, GO.

What is happening?

Can you change to another word? How?

Program 9 Using LCD display

```
7200      LCD_CWR: EQU 7200H
7201      LCD_DWR: EQU 7201H
7202      LCD_CRD: EQU 7202H
7203      LCD_DRD: EQU 7203H

8000          ORG 8000H
8000 30 0A          BR MAIN

                ; LCD DRIVERS

8002 D0          RET_LCD1: SEP R0

8003 05          LCD_READY: LDN R5
8004 FA 80          ANI 80H
8006 3A 03          BNZ LCD_READY

8008 30 02          BR RET_LCD1

800A F8 72 B4 F8  MAIN: LOAD R4, LCD_CWR
800E 00 A4

8010 F8 72 B5 F8          LOAD R5, LCD_CRD
8014 02 A5

8016 F8 72 B6 F8          LOAD R6, LCD_DWR
801A 01 A6

801C F8 80 B3 F8          LOAD R3, LCD_READY
8020 03 A3

8022 D3          SEP R3 ; wait until ready
8023 F8 01          LDI 1 ; clear display command
8025 54          STR R4 ; write to command register
```


8026	D3	SEP R3 ; wait until ready
8027	F8 41	LDI 'A' ; load D with ASCII 'A'
8029	56	STR R6 ; write to data register
802A	D3	SEP R3
802B	F8 42	LDI 'B'
802D	56	STR R6
802E	00	IDL ; stop here

This lab will need LCD module. Any text LCD with HD44780 compatible controller can be used.

Care should be taken, turn power off before Insert/Remove the LCD module! Ensure pin position before turn the power on!

The example was tested with standard 16x2 text LCD display.

The LCD registers are Command and Data registers. Both registers are READ and WRITE.

To use the LCD, it must be initialized, settings mode, clear memory. This was done under system monitor when RESET.

The LCD is rather slow device, so its command register then provides BUSY bit for indicating the ready for command or data reception.

R3 is pointed to subroutine to test this bit. First we send command 1 to command register to clear the display. The start location to be printed character is then at the TOP/LEFT.

Now we write the ASCII code for letter 'A' to data register and followed with 'B'.

Enter the code and run it. What is happening?

Can you put your name on the LCD by entering code manually?
How?

Program 10 UART communication

```
7305          UART_STATUS: EQU 7305H
7300          UART_BUFFER: EQU 7300H

8000          ORG 8000H

8000 30 0D          BR MAIN

8002 D0          RET_COUT: SEP R0

8003 A3          COUT: PLO R3

8004 04          COUT1: LDN R4
8005 FA 20          ANI 20H ; test TE flag
8007 32 04          BZ COUT1
8009 83          GLO R3
800A 55          STR R5
800B 30 02          BR RET_COUT

800D F8 73 B4 F8  MAIN: LOAD R4, UART_STATUS
8011 05 A4
8013 F8 73 B5 F8          LOAD R5, UART_BUFFER
8017 00 A5
8019 F8 80 B8 F8          LOAD R8, COUT
801D 03 A8

801F F8 41          LOOP: LDI 'A'
8021 D8          SEP R8
8022 30 1F          BR LOOP
```

This lab will test serial communication between the CDP1802 kit and the terminal. Communication format is asynchronous 9600 bit/s, 8 data bit no parity and one stop bit.

The onboard UART chip is INS8250. The chip was initialized by system monitor.

This lab demonstrates how to send the ASCII character from the kit to 9600 terminal. RS232 cross cable will be used to connect between the kit and terminal.

R4 is loaded with UART status register. R5 is loaded with UART Buffer register.

COUT is a subroutine that writes D register to the UART buffer. The TE bit is tested, until set. Then write D register to UART buffer. The UART hardware will convert parallel data into 10 bits serial data stream. The format includes start bit, 8-data bit and one stop bit.

Enter the code and run it. What is happening?

Can you print your name on terminal? How?

The terminal accepts control ASCII code that makes a new line. Try sending codes 0D (CR), 0A (LF) at the end of the string being sent.